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Model Function Based Conditional Gradient Method with Armijo-like Line Search



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Classic Conditional Gradient Method

Constrained Smooth Optimization Problem:

$$\min_{x \in C} f(x)$$

 $ightharpoonup C \subset \mathbb{R}^N$ compact and convex constraint set

Conditional Gradient Method: Update step:

$$y^{(k)} \in \underset{y \in C}{\operatorname{argmin}} \left\langle \nabla f(x^{(k)}), y \right\rangle$$
$$x^{(k+1)} = \gamma_k y^{(k)} + (1 - \gamma_k) x^{(k)}$$

Convergence mainly relies on:

- ▶ step size $\gamma_k \in [0,1]$ (we consider Armijo line search)
- ► **Descent Lemma** (implies curvature condition)

Generalizing the Descent Lemma

Descent Lemma:

$$|f(x) - f(\bar{x}) - \langle \nabla f(\bar{x}), x - \bar{x} \rangle| \le \frac{L}{2} ||x - \bar{x}||^2$$

- ▶ f smooth non-convex
- ightharpoonup L is the Lipschitz constant of ∇f

Generalizing the Descent Lemma

Generalization of the Descent Lemma:

$$|f(x) - f(\bar{x}) - \langle \nabla f(\bar{x}), x - \bar{x} \rangle| \le \omega(\|x - \bar{x}\|)$$

provides a measure for the linearization error

 \leadsto growth given by ω

- f smooth non-convex
- $\blacktriangleright \ \omega \colon \mathbb{R}_+ \to \mathbb{R}_+$ is a growth function

Generalizing the Descent Lemma

Generalization of the Descent Lemma:

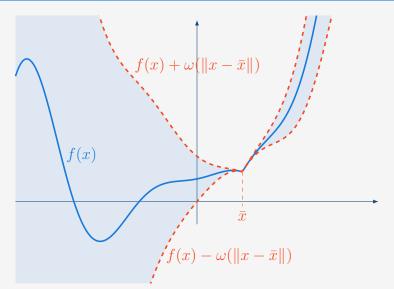
$$|f(x) - f_{\bar{x}}(x)| \le \omega(||x - \bar{x}||)$$

provides a measure for the **approximation error**

 \rightarrow growth given by ω

- f non-smooth non-convex
- $\blacktriangleright \ \omega \colon \mathbb{R}_+ \to \mathbb{R}_+$ is a growth function

Model Assumption $|f(x) - f_{\bar{x}}(x)| \le \omega(\|x - \bar{x}\|)$





Model Function based Conditional Gradient Method

Model Function based Conditional Gradient Method:

$$y^{(k)} \in \underset{y \in C}{\operatorname{argmin}} f_{x^{(k)}}(y)$$

 $x^{(k+1)} = \gamma_k y^{(k)} + (1 - \gamma_k) x^{(k)}$

Examples for Model Assumption: $|f(x) - f_{\bar{x}}(x)| \le \omega(\|x - \bar{x}\|)$

additive composite problem:

$$\min_{x \in C} \left\{ f(x) = \underset{\text{non-smooth}}{g(x)} + h(x) \right\}$$

- **model function:** $f_{\bar{x}}(x) = g(x) + h(\bar{x}) + \langle \nabla h(\bar{x}), x \bar{x} \rangle$
- ▶ oracle: $\underset{y \in C}{\operatorname{argmin}} g(y) + \langle \nabla h(x^{(k)}), y \rangle$

Examples

Examples for Model Assumption: $|f(x) - f_{\bar{x}}(x)| \le \omega(||x - \bar{x}||)$

hybrid Proximal–Conditional Gradient, example:

$$\min_{\substack{x_1 \in C_1 \\ x_2 \in C_2}} \{f(x_1, x_2) = g(x_1) + h(x_2)\}$$
 non-smooth smooth

 $f_{\bar{x}}(x_1, x_2) = h(\bar{x}_2) + \langle \nabla h(\bar{x}_2), x_2 - \bar{x}_2 \rangle + g(x_1) + \frac{1}{2\lambda} ||x_1 - \bar{x}_1||^2$

Examples

- composite problem
- second order Conditional Gradient

Design model functions for your problem!